



Welaptega SAMIR

Semi-Autonomous Mooring Inspection Robot

SAMIR combines visual inspection, photogrammetric measurement and Magnetic Flux Leakage (MFL) technology to assess the in-service condition of sheathed and unsheathed wire moorings lines.

SAMIR is deployed to the wire by ROV and is self-propelled using integrated electric drive wheels. Inspection data and tool telemetry are transmitted to the topside data recording and processing system which can then provide results in real-time.

Applications

- UWILD wire rope inspection (external + internal)
- Class survey wire rope inspection (external + internal)
- Wire rope diameter measurements

Features

- Internal, quantifiable wire rope inspection using advanced magnetic NDT
- Provides 360 degree close visual inspection of the exterior condition
- Provides objective quantitative inspection of internal defects that cannot be seen by visual inspection alone
- Inspect without impact to production
- Measures inclination and depth location of anomalies
- Designed in consultation with rope manufacturers

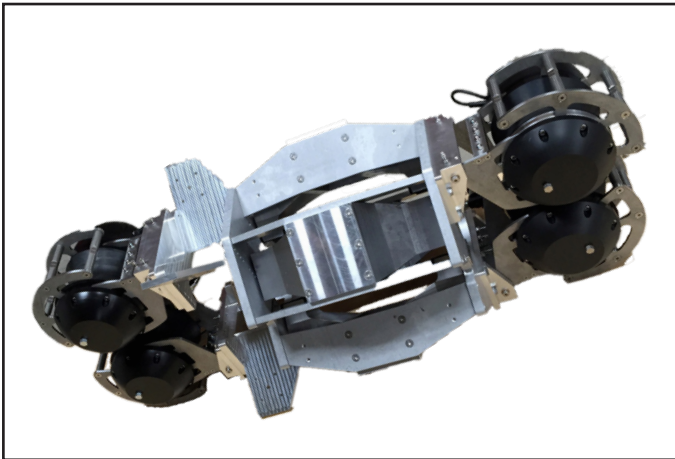


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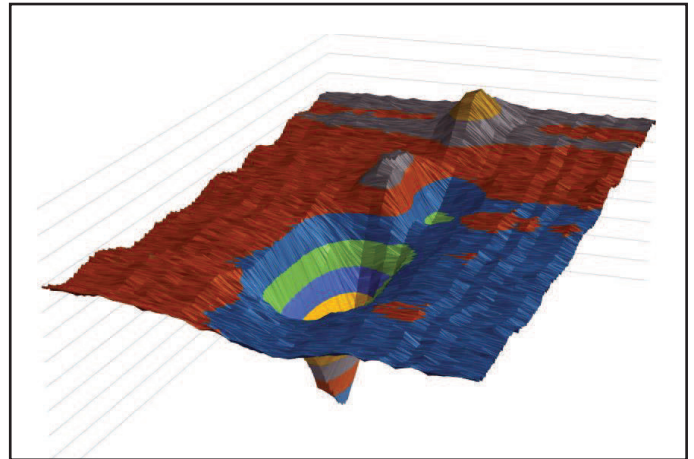
Specifications



System components	Composite frame Buoyancy to reduce in-water weight Fail-safe design ensures ROV and tool are always retrievable Topside fibre optic data transmission and analysis system
Deployment requirements	Work-class ROV Four video lines Hydraulic supply 3000psi working pressure Dedicated single-mode fiber 120 AC 10 amps power supply



SAMIR without buoyancy



Sample data output showing two peak and valley patterns
Representing two Broken wires in close proximity

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